

### Figure 1: The VC-1 Aircraft Model

# VERDECOMMUTE

VC-1 "AMPED" CONFIGURATION EVALUTATION

An aircraft purpose built for the Regional Air Mobility Market, leveraging VerdeGo's hybrid powerplants.

Team Lead: Gabriel Rodriguez

Team Members: Gregory Callaghan, Daniel Rodriguez,

Walker Wood, Holden Smith

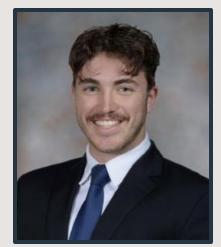
### **TEAM MEMBER INTRODUCTION**



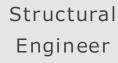
Gabriel Rodriguez



Walker Wood



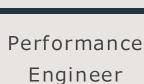
Holden Smith



Drag Modeling, Structural Analysis



Daniel Rodriguez



Performance Analysis, Mission Analysis



**Gregory Callaghan** 

Controls Engineer

Lift Modeling, Stability Analysis, Constraint Analysis

### Principal Investigator

Detailed Weight Modeling, Cost Analysis, Systems Integration, Propulsion Design Engineer

Solid Modeling, Systems Integration, Stability Analysis

### 1. AIRCRAFT AND STAKEHOLDER INTRODUCTION

- 2. DESIGN MISSION AND REQUIREMENTS
- 3. DEVELOPMENT SUMMARY
- 4. CONSTRAINT ANALYSIS AND TRADE STUDIES
- 5. CONFIGURATION SELECTION AND LAYOUT
- 6. WEIGHT MODELING AND MASS PROPERTIES
- 7. AERODYNAMICS AND SENSITIVITY ANALYSIS
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- 12.CONCLUSION
- 13.REFERENCES

# **PRIMARY** MISSION AND **STAKEHOLDERS**

#### THE VC-1 "AMPED"

- Hybrid-Electric STOL (Short Take-Off and Landing)
- Designed for Regional Air Mobility
- Carries 7 passengers or 1,575 [lbs] payload over a 438 [*nm*] range

#### **OUR PRIMARY MISSION**

- Connect under-utilized regional airports, enabling faster travel between cities
- Increase sustainability and lower operating costs

#### **OUR STAKEHOLDERS**













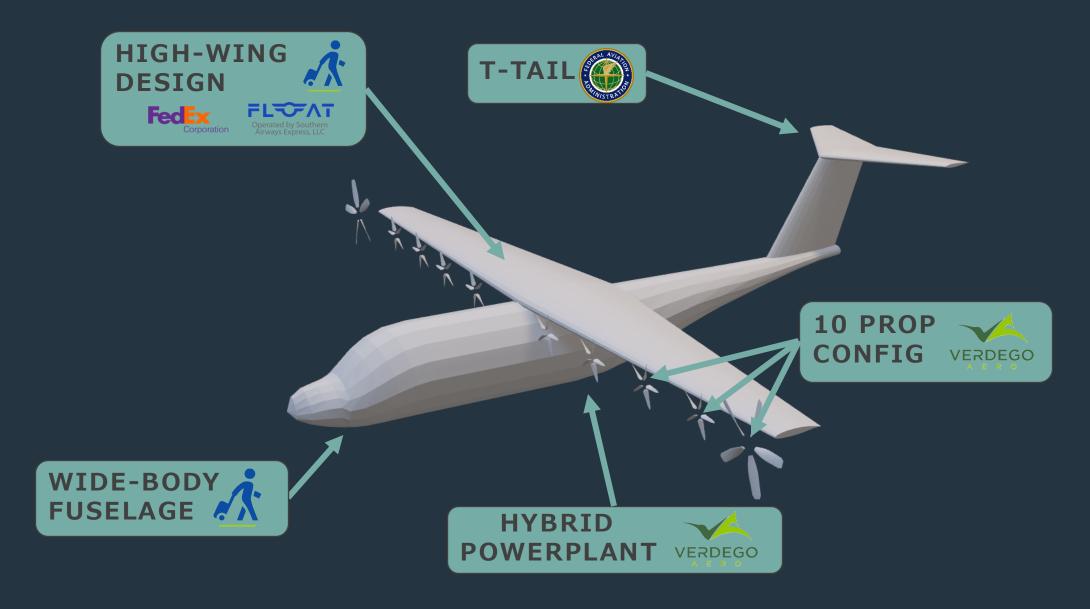






Figure 2: VC-1 Stakeholders

# VC-1 "AMPED" KEY FEATURES



1. AIRCRAFT AND STAKEHOLDER INTRODUCTION

### 2. DESIGN MISSION AND REQUIREMENTS

- 3. DEVELOPMENT SUMMARY
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- 5. CONFIGURATION SELECTION AND LAYOUT
- 6. WEIGHT MODELING AND MASS PROPERTIES
- 7. AERODYNAMICS AND SENSITIVITY ANALYSIS
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- 12.CONCLUSION
- 13.REFERENCES

### **DESIGN MISSION PROFILE**

#### **KEY CHARACTERISTICS**

- Distributed Electric
  Propulsion Enabled
  Short Take-Off
- Hybrid-Electric Powerplant
- Short Landing

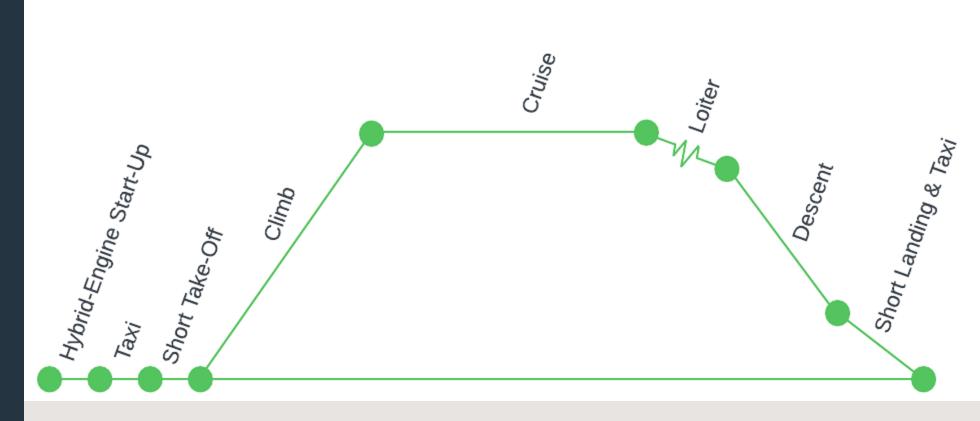


Figure 4: The VC-1 Design Mission Profile

# MISSION REQUIREMENTS

REQUIREMENT	SOURCE	VALUE	STATUS
Number of Passengers + Crew	RFP	8 [persons]	✓
Range	RFP	275 [ <i>nm</i> ]	✓
Cruise Speed	RFP	150 [ <i>KTAS</i> ]	✓
Take-Off Ground Roll	RFP	500 [ft]	✓
Landing Ground Roll	RFP	500 [ft]	✓
Propulsion System	RFP	DEP, Hybrid	✓
Rate of Climb (ROC)	14 CFR	1,100 [ft/s]	✓
Service Ceiling	14 CFR	10,000 [ft]	✓
Cruise Altitude	VC	8,000 [ft]	✓

# SIMILAR DEP AIRCRAFT

Basic Requirements	VC-1 "Amped"	Maxwell X-57	Electra Concept
Number of Passengers + Crew	8 [persons]	2 [persons]	9 [persons]
Range	438 [nm]	87 [nm]	1,100 [nm]
Cruise Speed	150 [KTAS]	150 [KTAS]	175 [KTAS]
Take-Off Ground Roll Distance	393 [ft]	1,600 [ft]	150 [ft]

### Maxwell X-57



Figure 5: The X-57 (DEP configuration), sourced from nasa.gov

### **Electra Concept**



Figure 6: The Electra concept, sourced from electra.aero

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- 4. CONSTRAINT ANALYSIS AND TRADE STUDIES
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- 6. WEIGHT MODELING AND MASS PROPERTIES
- 7. AERODYNAMICS AND SENSITIVITY ANALYSIS
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- 11.COST ANALYSIS
- 12.CONCLUSION
- 13.REFERENCES

## FISHBONE DIAGRAM

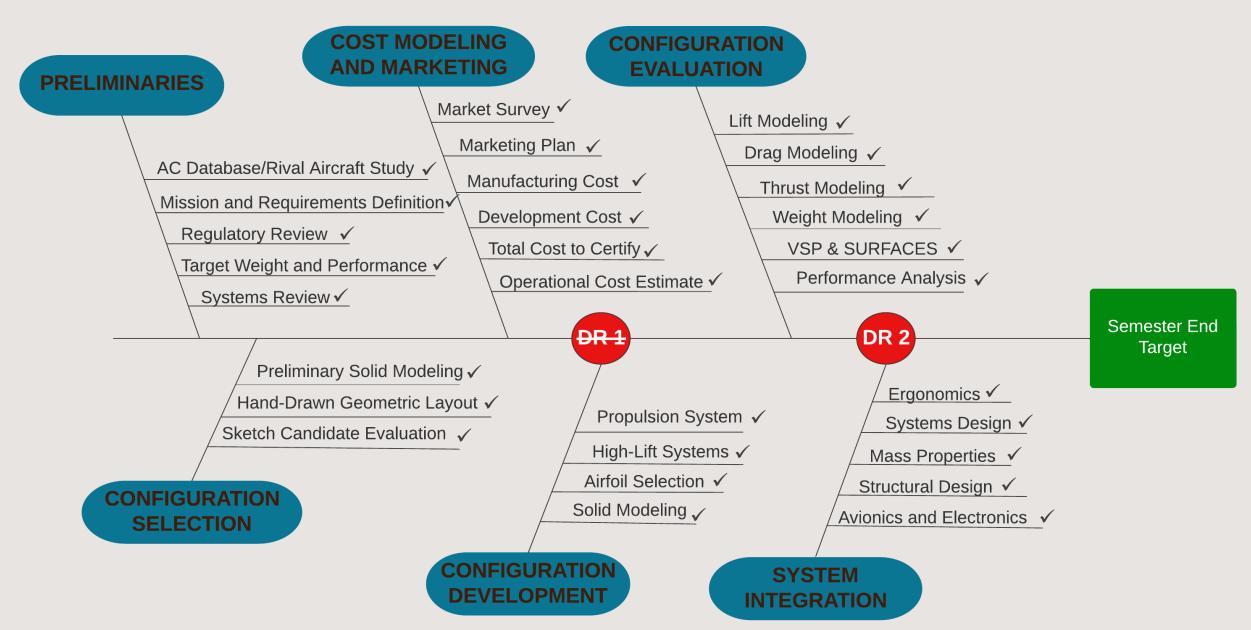
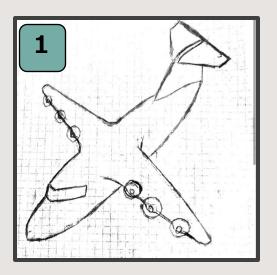
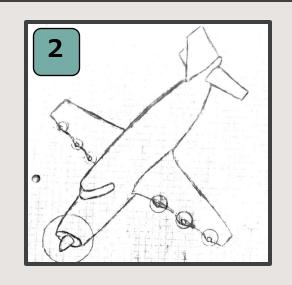
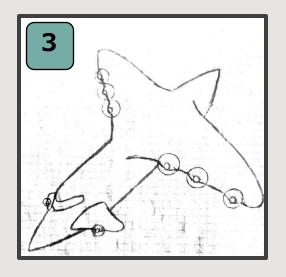


Figure 7: The Fishbone diagram, created using Lucid.

# **CONFIGURATION SELECTION**







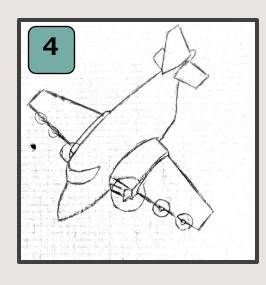


Figure 8: Initial configuration concepts.

### MAIN CONSIDERATIONS:

- Ground Roll Take-Off Distance
- Cost Estimation
- Payload Capacity
- Noise Minimization



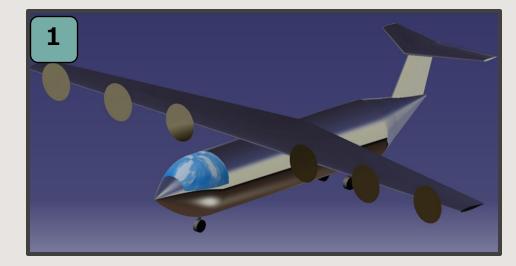


Figure 9: Preliminary solid model of selected configuration.

# KEY CONFIGURATION CHANGES



Figure 10: The VH-3 Engine, sourced from verdegoaero.com

### **Powerplant Selection**

Two VH-3's  $\Rightarrow$  One VH-4T 4920 [lbs]  $\Rightarrow$  7200 [lbs]

Oct. 20th



Figure 11: The VH-4T Engine, sourced from verdegoaero.com

### **Distributed Electric Propulsion**

6 Thrust Propellers ⇒ 2 Thrust Propellers + 8 High Lift Propellers

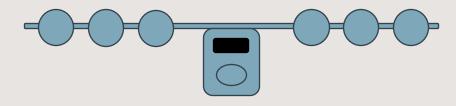


Figure 12: The initial DEP configuration.



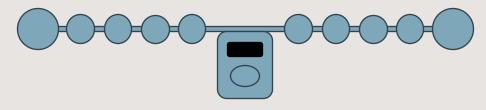


Figure 13: The final DEP configuration

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- 6. WEIGHT MODELING AND MASS PROPERTIES
- 7. AERODYNAMICS AND SENSITIVITY ANALYSIS
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### **CONSTRAINT ANALYSIS**

# Three Potential Design Points:

- Wing loading 23 [lb/sf]
  - Prioritizes ground roll
- Wing loading 26 [lb/sf]
  - Closest to all constraints
- Wing loading 30 [lb/sf]
  - Prioritizes cruise

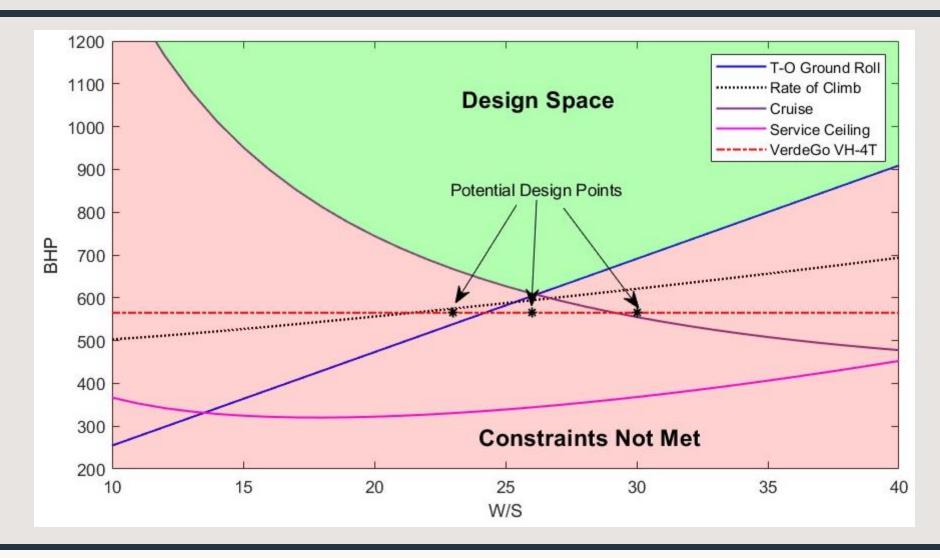


Figure 14: The VC-1's Constraint Analysis Map

### CONSTRAINT ANALYSIS CONT.

### **Ground Roll Prioritized:**

- 23 [*lb/sf*]
- Most important to regional air mobility mission

### VH-4T Max Power Output:

- 556 [hp]
- Battery usage avoided to reduce weight

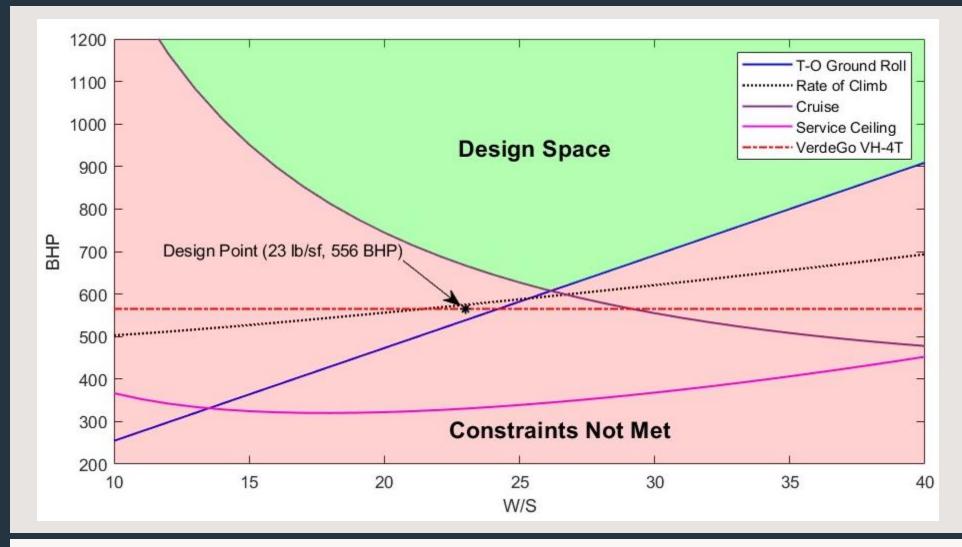


Figure 15: The VC-1's Constraint Analysis Map

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- 4. CONSTRAINT ANALYSIS AND TRADE STUDIES

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# **CAD RENDERINGS**

DR1 DR2

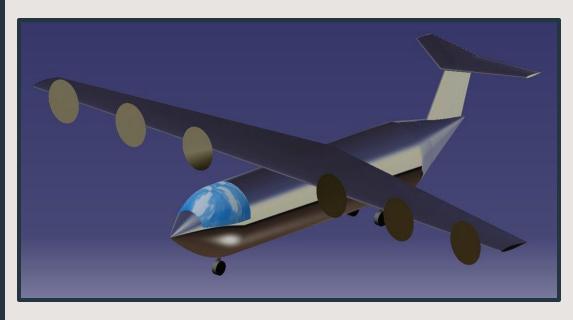


Figure 16: Preliminary CAD Model

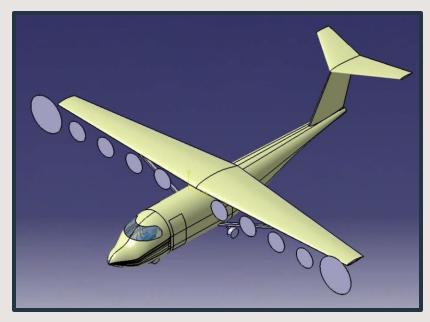
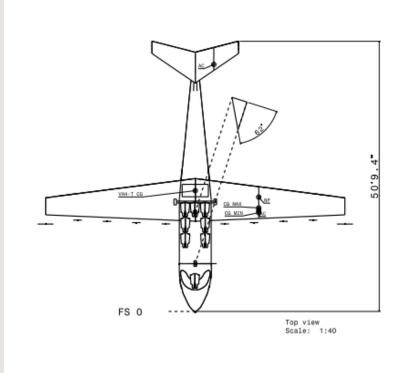
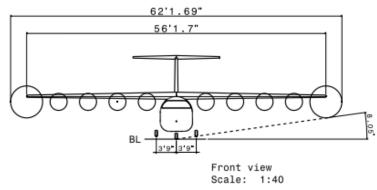


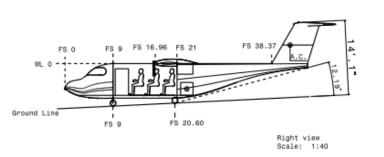
Figure 17: Current CAD Model

# 3-VIEW DRAWING

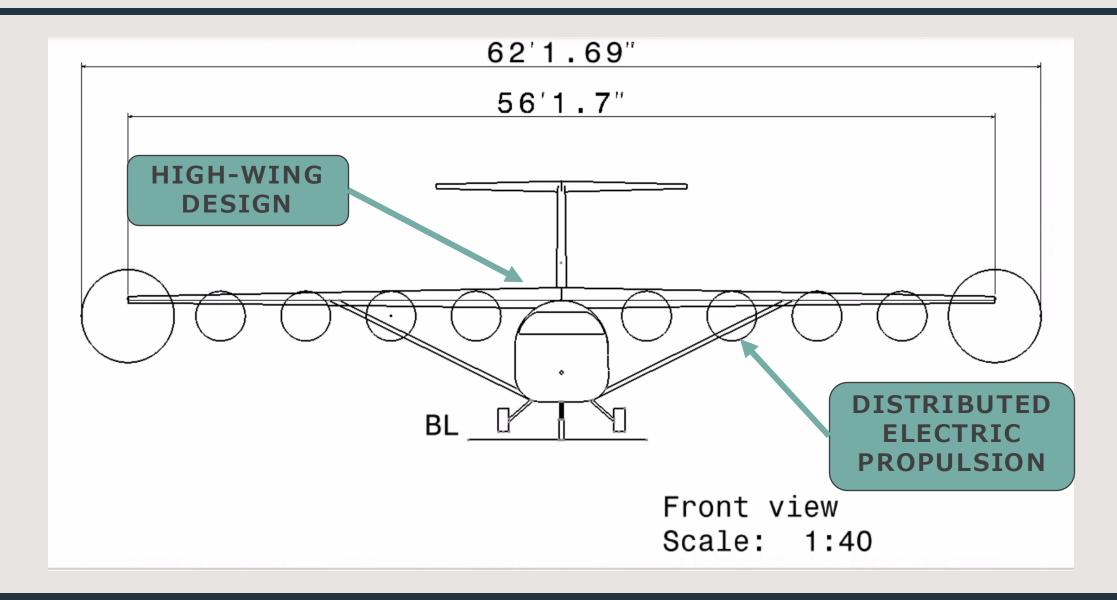


	Wing	HT	VT
SPAN (FT)	56.14	16.25	7.43
AREA (FT^2)	315.22	66.08	42.47
MGC (ft)	5.96	4.31	5.77
ASPECT RATIO	10	4	1.3
FS LE MGC	17.48	28.89	23.92
FS AC	18.97	29.97	25.36
BL MGC	12.03	3.48	3.5
ROOT AIRFOIL	NASA	NACA	NACA
	LS(1)-0417	0012	0014
TIP AIRFOIL	NASA	NACA	NACA
	LS(1)-0413	0012	0014
CL ALPHA	5.6148	3.6837	
CM ALPHA	-0.0634	-2.214	
CMCL	-0.0133	-0.601	

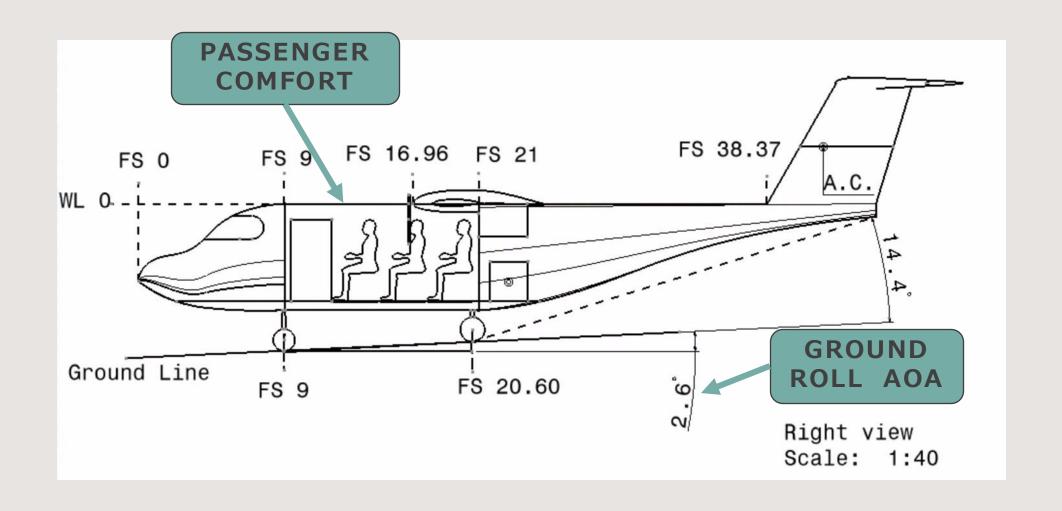




### FRONT VIEW KEY FEATURES



# RIGHT VIEW KEY FEATURES



### **CROSS-SECTIONAL VIEW**

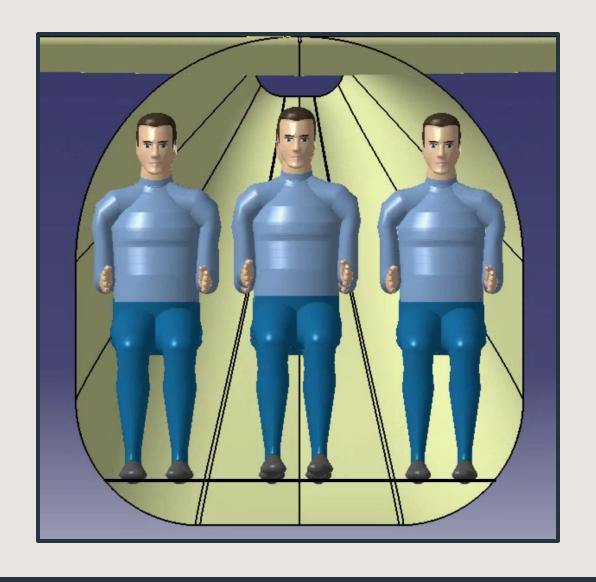


Figure 21: VC-1 Cross-Sectional View

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- 4. CONSTRAINT ANALYSIS AND TRADE STUDIES
- 5. CONFIGURATION SELECTION AND LAYOUT

#### 6. WEIGHT MODELING AND MASS PROPERTIES

- 7. AERODYNAMICS AND SENSITIVITY ANALYSIS
- 8. PROPULSION AND THRUST GENERATION
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- 10.STABILITY & CONTROL
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- 12.CONCLUSION
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# **WEIGHT COMPONENTS**

### **KEY CHARACTERISTICS**

- Sized Batteries toSmooth Power from thePowerplant
- Weight ∝ Ground Roll

GROUND ROLL TRADE STUDY				
<b>5500</b> [/bs]	<b>268</b> [ft]			
<b>6500</b> [/bs]	<b>352</b> [ft]			
<b>7200</b> [lbs]	<b>393</b> [ft]			

WEIGHT (lbs)
2311
809
441
811
1000
1800
7172

# MASS PROPERTIES

#### **KEY CHARACTERISTICS**

- Seating will start from the rear, and progress forward
- Limits taken from S&C analysis, further constrained based on desirable conditions and similar aircraft

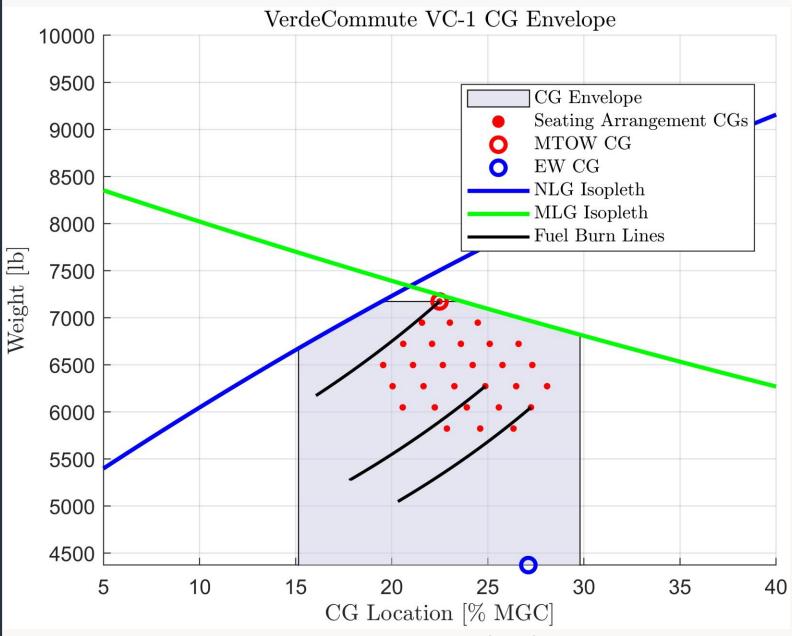


Figure 22: VC-1 CG Envelope Plot

- 1. AIRCRAFT AND STAKEHOLDER INTRODUCTION
- 2. DESIGN MISSION AND REQUIREMENTS
- 3. DEVELOPMENT SUMMARY
- 4. CONSTRAINT ANALYSIS AND TRADE STUDIES
- 5. CONFIGURATION SELECTION AND LAYOUT
- 6. WEIGHT MODELING AND MASS PROPERTIES

### 7. AERODYNAMICS AND SENSITIVITY ANALYSIS

- 8. PROPULSION AND THRUST GENERATION
- 9. PERFORMANCE
- 10.STABILITY & CONTROL
- 11.COST ANALYSIS
- 12.CONCLUSION
- 13.REFERENCES

# **AIRFOIL SELECTION**

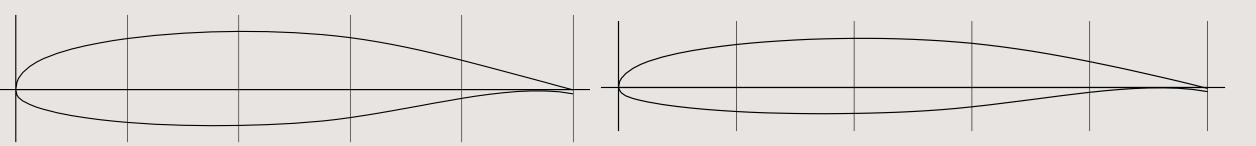
#### **DESIRED CHARACTERISTICS:**

- High L/D
- High  $C_{L,MAX}$
- Drag Bucket around  $C_L$  of 0.4
- Benign Stall
- Natural Laminar Flow (NLF)

Airfoil	Ideal C <sub>L</sub>	Max L/D	NLF	$C_{L,MAX}$	Benign Stall	t/c
Clark Y	0.55	111	N	1.56	N	0.117
NACA 23112	0.2	98	N	1.55	N	0.12
NACA 4412	0.6	97	N	1.51	N	0.12
NACA 63-415	0.4	96	Υ	1.26	Y	0.15
NASA LS(1)-0417	0.5	112	Υ	1.75	Υ	0.17
NASA LS(1)-0413	0.5	115	Υ	1.75	Y	0.13

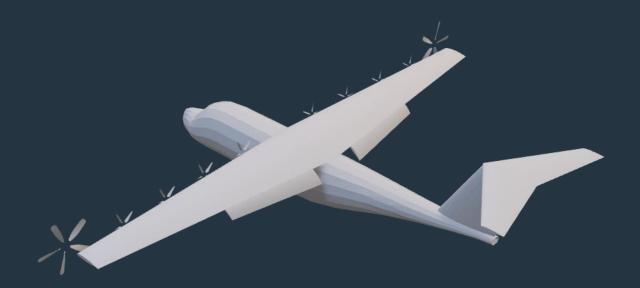
**TIP:** NASA LS(1)-0413

**ROOT:** NASA LS(1)-0417 (GA(W)-1)



# FLIGHT CONFIGURATIONS





Cruise

Figure 23: VC-1 Cruise Configuration

**Take-off and Landing** 

Figure 24: VC-1 Cruise Configuration

### **FLIGHT CONFIGURATIONS**

#### **CRUISE**

- Propellers cause minimal lift augmentation
- Tail trimmed for no control deflection
- Cruise C<sub>L</sub> in drag bucket

#### **TAKE-OFF & LANDING**

- Single slotted fowler flaps
  - 40 degree deflection
  - Half exposed span
- HLPs increase lift by 25%

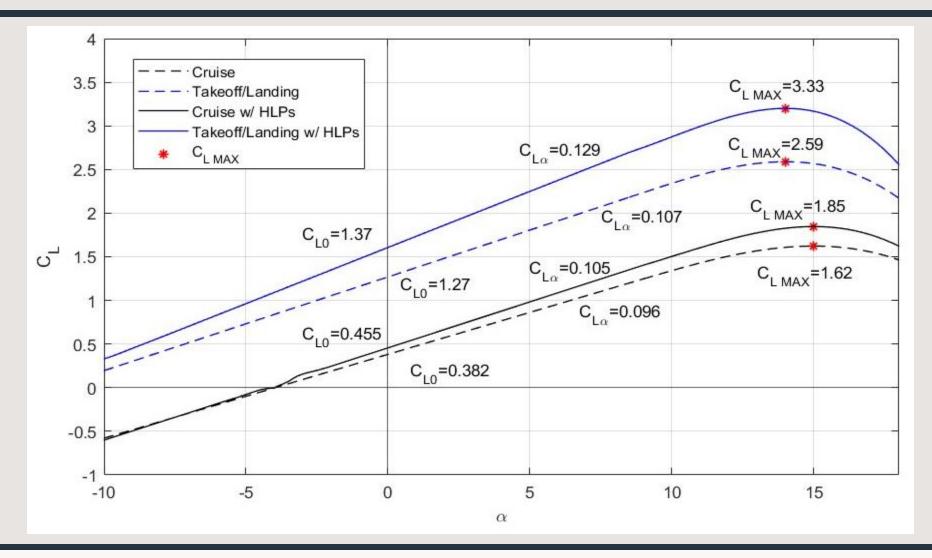


Figure 25: VC-1 Lift Modeling

# DRAG CONFIGURATIONS

#### **CRUISE**

- Trimming for stability results in minor drag
- High aspect ratio
   reduces induced drag for
   efficient cruise

### TAKE-OFF & LANDING

- Fowler flaps and HLPs increase  $C_{D_i}$
- Similar drag for both

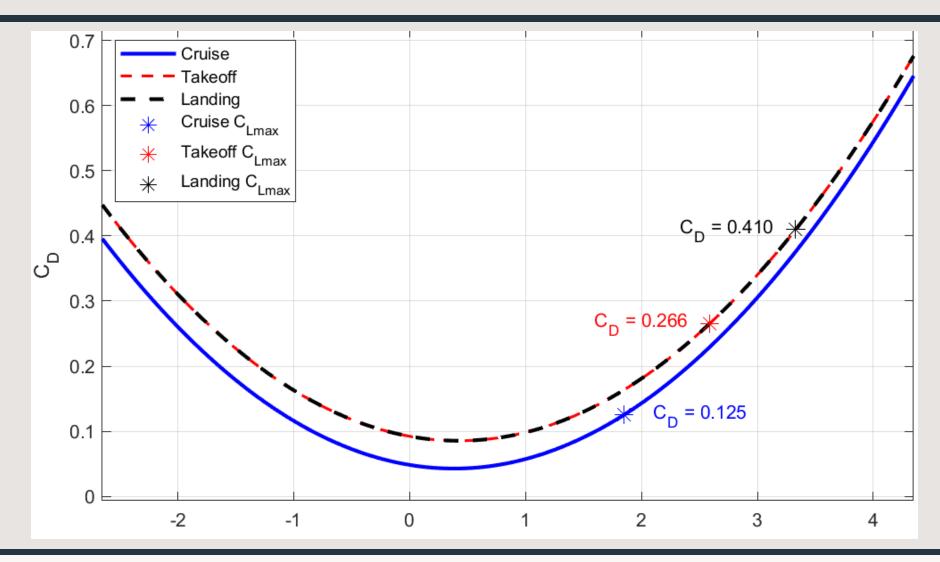


Figure 26: VC-1 Drag Modeling

- 1. AIRCRAFT AND STAKEHOLDER INTRODUCTION
- 2. DESIGN MISSION AND REQUIREMENTS
- 3. DEVELOPMENT SUMMARY
- 4. CONSTRAINT ANALYSIS AND TRADE STUDIES
- 5. CONFIGURATION SELECTION AND LAYOUT
- 6. WEIGHT MODELING AND MASS PROPERTIES
- 7. AERODYNAMICS AND SENSITIVITY ANALYSIS

### 8. PROPULSION AND THRUST GENERATION

- 9. PERFORMANCE
- 10.STABILITY & CONTROL
- 11.COST ANALYSIS
- 12.CONCLUSION
- 13.REFERENCES

## POWERPLANT SELECTION

### TWO VH3-185 KW



Figure 27: Sourced from VerdeGo Aero Website verdegoaero.com/

MTOW: 7930 [/bs]
Battery Weight: 450 [/bs]
Less Desirable

### ONE VH4T-400 KW



Figure 28: Sourced from VerdeGo Aero Website verdegoaero.com/

MTOW: 6570 [lbs]
Battery Weight: 150 [lbs]
Maximum Efficiency

### RESULTING THRUST MODEL

#### **KEY CHARACTERISTICS**

- *Maximizing Thrust at Take-off*
- Stopped High Lift
  Propellers at 90 KTAS
- 74% Power Usage at Cruise

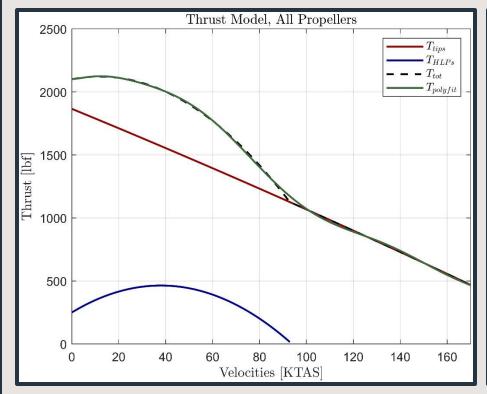


Figure 29: Thrust model across velocities, sea-level.

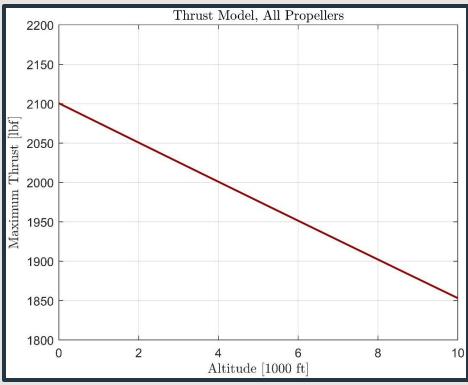


Figure 30: Maximum thrust across operating altitudes.

- 1. AIRCRAFT AND STAKEHOLDER INTRODUCTION
- 2. DESIGN MISSION AND REQUIREMENTS
- 3. DEVELOPMENT SUMMARY
- 4. CONSTRAINT ANALYSIS AND TRADE STUDIES
- 5. CONFIGURATION SELECTION AND LAYOUT
- 6. WEIGHT MODELING AND MASS PROPERTIES
- 7. AERODYNAMICS AND SENSITIVITY ANALYSIS
- 8. PROPULSION AND THRUST GENERATION

### 9. PERFORMANCE

- 10.STABILITY & CONTROL
- 11.COST ANALYSIS
- 12.CONCLUSION
- 13.REFERENCES

## **PERFORMANCE**

#### **KEY PERFORMANCE DATA**

Maximum Range TargetCruise: 438 [nm]

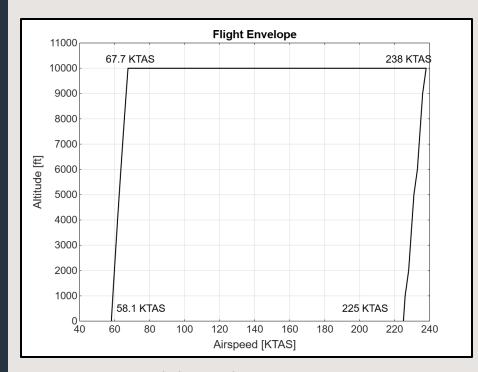


Figure 31: VC-1 Flight Envelope

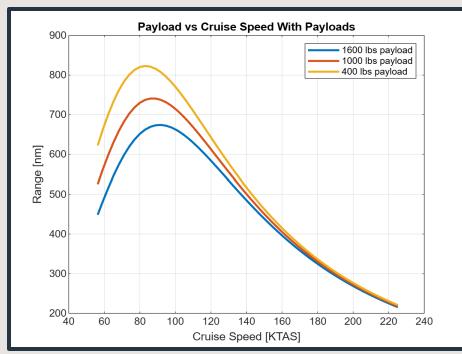


Figure 32: Range vs Airspeed for Payloads

## PERFORMANCE CONT.

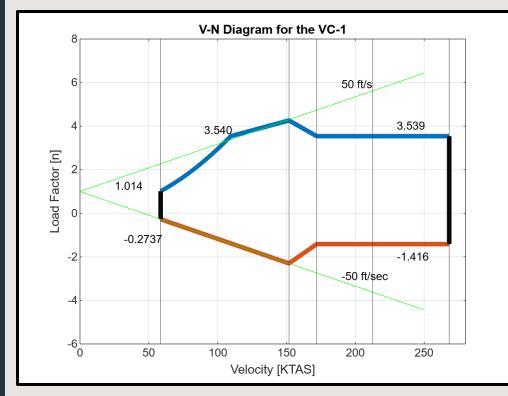


Figure 33: V-N diagram for the VC-1

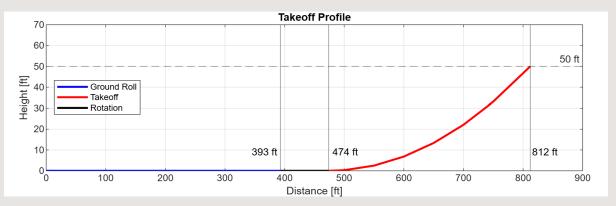


Figure 34: Takeoff profile of the VC-1

### **Take-off Performance Compared w/ Rivals**

Aircraft VC-1 "Amped"		Pilatus PC-6 STOL	Electra Concept
Ground Roll (ft)	393 [ft]	646 [ft]	150 [ft]

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- 2. DESIGN MISSION AND REQUIREMENTS
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- 6. WEIGHT MODELING AND MASS PROPERTIES
- 7. AERODYNAMICS AND SENSITIVITY ANALYSIS
- 8. PROPULSION AND THRUST GENERATION
- 9. PERFORMANCE

#### **10.STABILITY & CONTROL**

- 11.COST ANALYSIS
- 12.CONCLUSION
- 13.REFERENCES

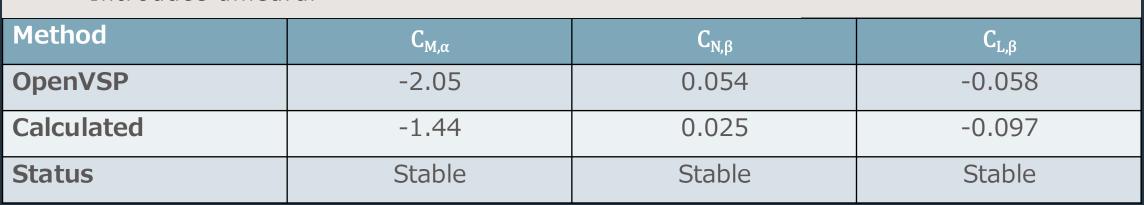
### STATIC STABILITY

#### **KEY CHARACTERISTICS:**

- Tail and fuselage sizes increased since DR1
- Directional and lateral stability remain low
  - Fuselage increase opposes tail increase
  - Handles neutrally for a passenger aircraft
  - Active control systems improve handling, safety, and comfort



- Increase vertical tail size
- Introduce dihedral



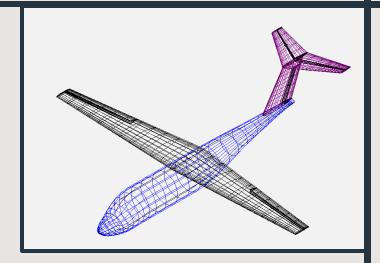
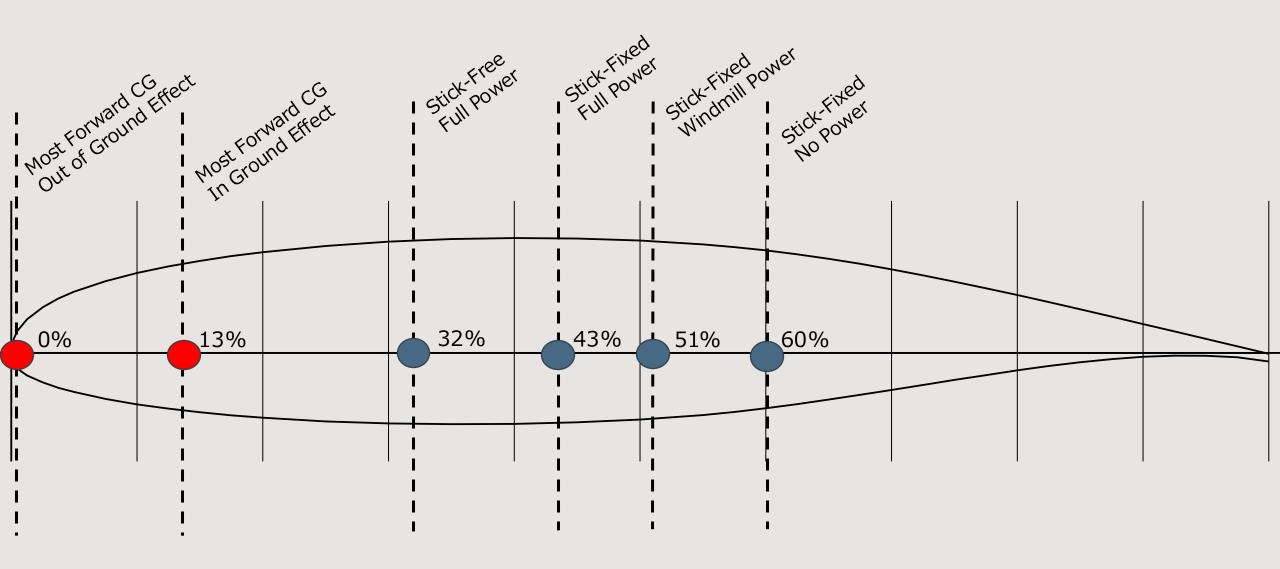


Figure 35: VC-1 OpenVSP Model

### **NEUTRAL POINTS AND FORWARD CG LOCATIONS**



# **DYNAMIC STABILITY**

#### PHUGOID MODE

- Lightly Damped
- Active control systems for passenger comfort
- Opportunities for improvement
  - Increase tail volume further

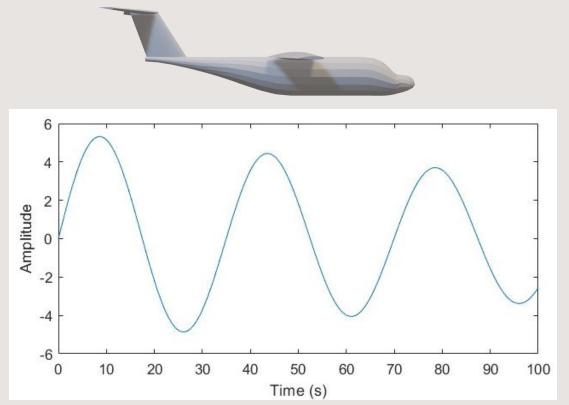


Figure 36: Phugoid Mode Plot

#### **SHORT PERIOD**

- Small oscillation damped out within 5 seconds
- Little affect on passenger comfort
- Further increases in tail volume would provide even more damping

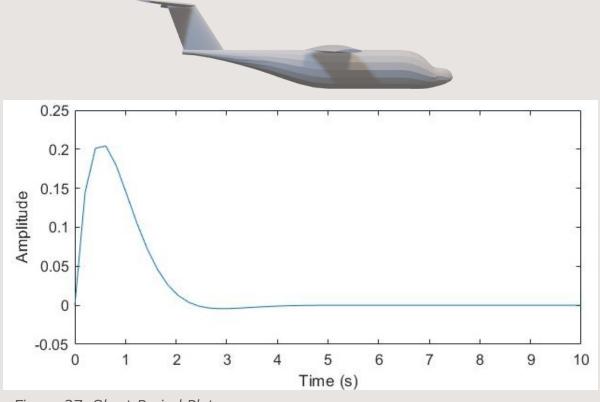


Figure 37: Short Period Plot

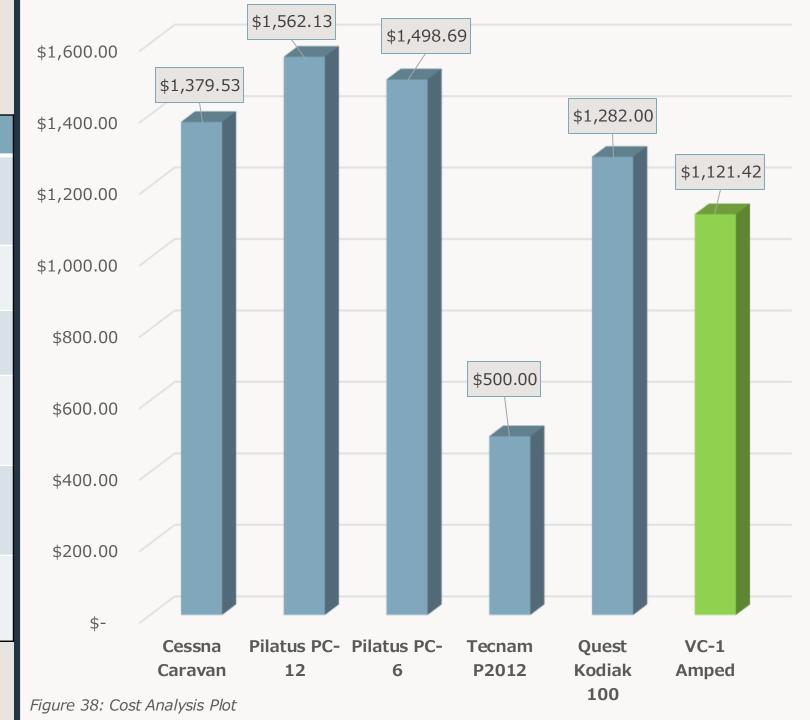
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- 2. DESIGN MISSION AND REQUIREMENTS
- 3. DEVELOPMENT SUMMARY
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- 7. AERODYNAMICS AND SENSITIVITY ANALYSIS
- 8. PROPULSION AND THRUST GENERATION
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- 10.STABILITY & CONTROL

#### 11.COST ANALYSIS

- 12.CONCLUSION
- 13.REFERENCES

### **COST ANALYSIS**

	Cost Estimates [\$]
Total Development Cost	1,119,571,479
Variable Cost	2,155,900
Variable Cost with QDF	1,985,460
Yearly Operational Cost	2,803,560
Hourly Operational Cost	1121.42
Price	2,750,000



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- 9. PERFORMANCE
- 10.STABILITY & CONTROL
- 11.COST ANALYSIS

#### 12.CONCLUSION

13.REFERENCES

# CONCLUSION

#### The VC-1 is...

- Built for Regional Air Mobility
- Excelling in Take-OffDistance, OperatingCost, and Range
- Utilizing VerdeGo and NASA technologies
- Ready for detailed design
- > QUESTIONS?

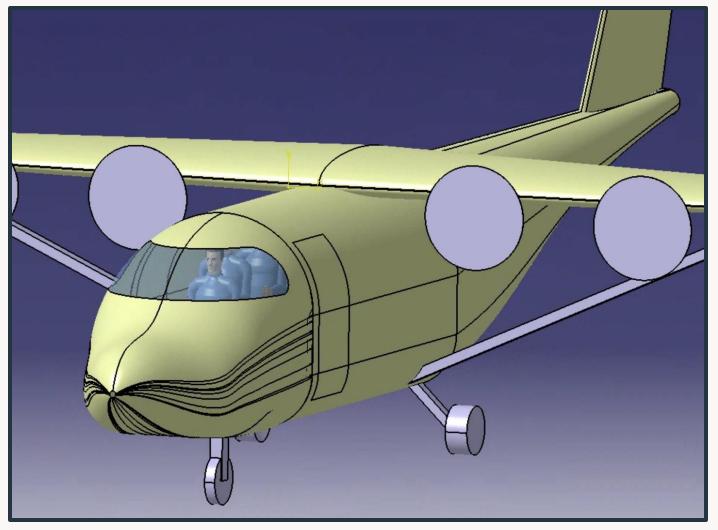


Figure 39: VC-1 CAD Model, with Pilot and Passengers

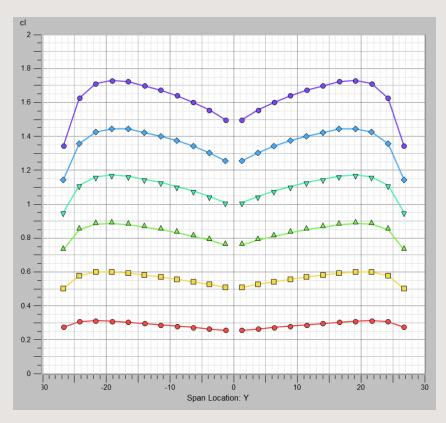
- 1. AIRCRAFT AND STAKEHOLDER INTRODUCTION
- 2. DESIGN MISSION AND REQUIREMENTS
- 3. DEVELOPMENT SUMMARY
- 4. CONSTRAINT ANALYSIS AND TRADE STUDIES
- 5. CONFIGURATION SELECTION AND LAYOUT
- 6. WEIGHT MODELING AND MASS PROPERTIES
- 7. AERODYNAMICS AND SENSITIVITY ANALYSIS
- 8. PROPULSION AND THRUST GENERATION
- 9. PERFORMANCE
- 10.STABILITY & CONTROL
- 11.COST ANALYSIS
- 12.CONCLUSION

#### 13.REFERENCES

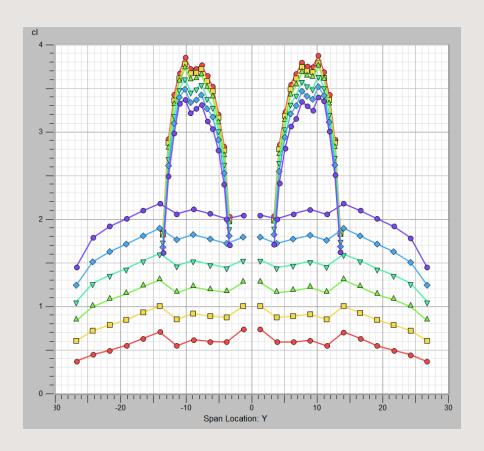
### REFERENCES SLIDE

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### LIFT DISTRIBUTION AND STALL

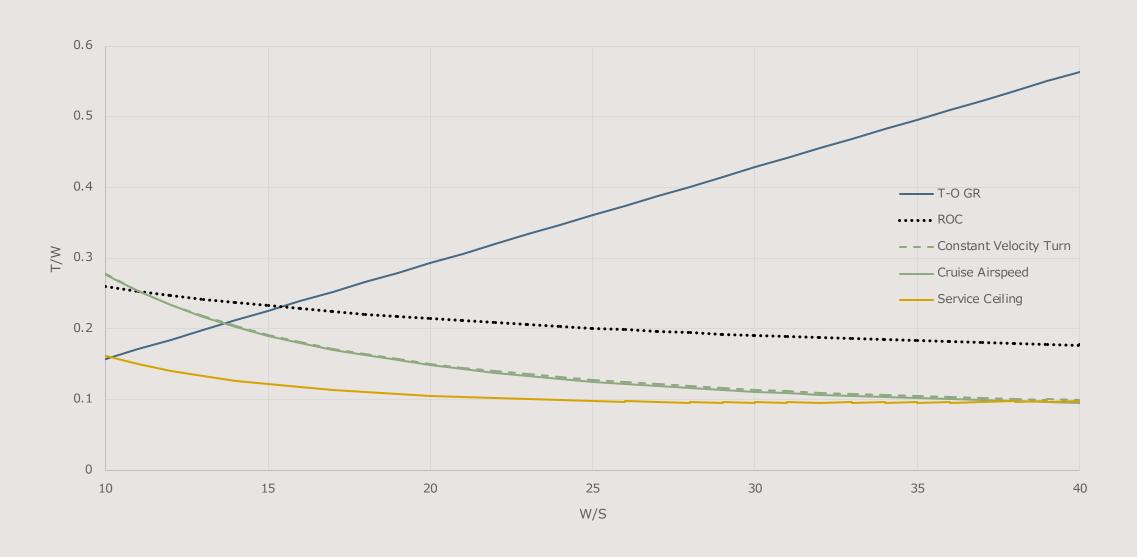


Cruise



**Flaps Down** 

# T/W CONSTRAINT GRAPH



### STABILITY DERIVATIVES

- VC-1 remains statically stable across flight conditions
- Pitch is lightly damped
- Roll is well damped
- Yaw is aptly damped

Damping	Derivatives
Pitch Damping	-32
Roll Damping	-0.80
Yaw Damping	-0.122

Takeoff Roll	Derivatives	Stable
Pitch	-0.173	Stable
Roll	-0.076	Stable
Yaw	0.177	Stable

Max AoA	Derivatives	Stable
Pitch	-5.95	Stable
Roll	-0.171	Stable
Yaw	0.213	Stable

### **CONTROL SURFACES**

#### **Elevator:**

- 50% chord
- Full span of HT
- Authority to reach CLMAX in takeoff configuration at takeoff speed
- Most forward CG at 13%
   MGC

#### **Ailerons:**

- Half exposed span
- 25% chord
- 9 degree deflection
- Roll helix of 0.088 radians
- High roll performance for authority at low speed

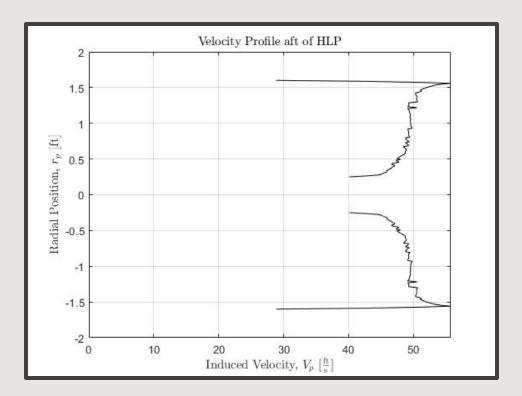
#### **Rudder:**

- Nearly full span of VT
- 50% chord
- Worst power case
  - Half total takeoff thrust on one tip propeller
  - Rudder cancels moment at 30 KTAS

### HIGH LIFT PROPELLER DESIGN

#### Why HLP's?

- Minimize Excess Thrust
- Induce a Constant Velocity Profile
- Maximize Lift Augmentation



#### **Designed Using BEMT:**

$$dT = 4\pi r \rho V_{\infty}^2 (1+a)adr$$

$$dT = Bc \frac{1}{2} \rho W^{2} (c_{l} \cos(\phi) - c_{d} \sin(\phi)) dr$$

